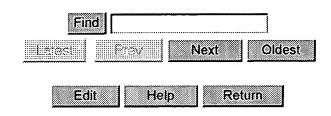
## Searches for User *gphilippe* (Count = 9717)

Queries 19335 through 19384.

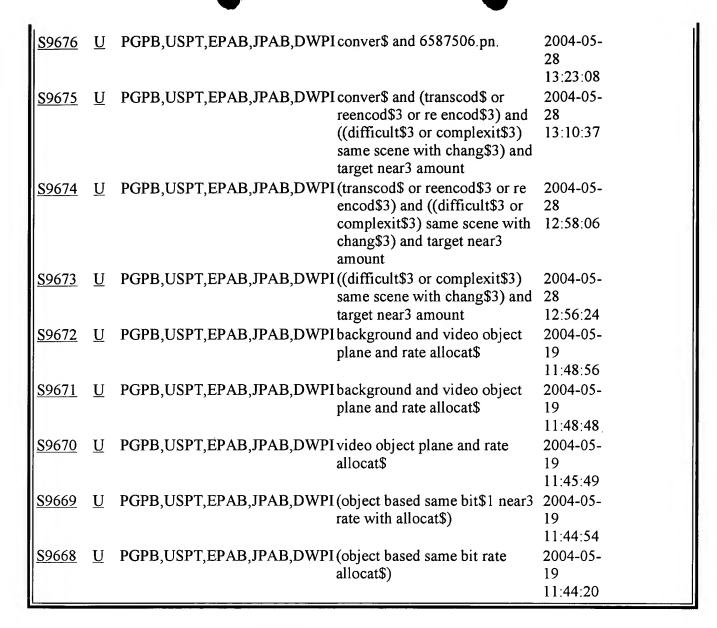


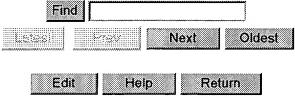
S#	Upd	t	Database	Query	Time	Comment
S9717	<u>U</u>	USPT		(linear\$ with matching with	2004-06-	
				error\$1 same grid\$1) and	03	
				motion vector\$1	12:47:48	
S9716	<u>U</u>	USPT		(linear\$ with matching error\$1	2004-06-	
				same grid\$1) and motion	03	
				vector\$1	12:47:26	
<u>S9715</u>	<u>U</u>	USPT		grid\$1 and 5668608.pn.	2004-06-	
					03	
00714		LICDE		<b>61</b> 1.6562070	12:37:48	
<u>S9714</u>	<u>U</u>	USPT		error\$1 and 6563872.pn.	2004-06- 03	
					12:24:40	
S9713	U	DCDR I	JSPT,EPAB,JPAB,DWPI	error\$1 and 6563872 nn	2004-06-	
39/13	<u>U</u>	r Or D, C		terror and 0303872.pm.	03	
					12:24:32	
S9712	U	PGPR I	JSPT,EPAB,JPAB,DWPI	grid\$1 and 6563872 nn	2004-06-	
32,12		1 01 2,0	, , , , , , , , , , , , , , , , , , ,	Silati and obostizipii.	03	
					12:18:07	
S9711	U	PGPB,U	JSPT,EPAB,JPAB,DWPI	distance and candidate\$1 and	2004-06-	
		,	, , ,	predict\$ and motion estimat\$	03	
				and (grid\$1 with points with	12:08:33	
				vector\$) and motion vector\$1		
S9710	<u>U</u>	PGPB,U		candidate\$1 and predict\$ and	2004-06-	
				motion estimat\$ and (grid\$1	03	
				with points with vector\$) and	11:51:04	
				motion vector\$1		A #
<u>S9709</u>	<u>U</u>	PGPB,U	JSPT,EPAB,JPAB,DWPI	predict\$ and motion estimat\$	2004-06-	- 11
				and (grid\$1 with points with	03	
0700	ŢŢ	DCDD I		vector\$) and motion vector\$1	11:50:38	
<u>S9708</u>	<u>U</u>	rupb,U		motion estimat\$ and (grid\$1 with points with vector\$) and	2004-06- 03	
				motion vector\$1	11:50:21	
S9707	U	PGPR I	JSPT,EPAB,JPAB,DWPI	- 1 - 1 - 1 - 1 - 1 - 1 - 1 - 1	2004-06-	
<del>37/0/</del>	<u>U</u>	, U. D, C		vector\$) and motion vector\$1	03	
				. cotory, and motion votory?	<b>5</b> 5	

1.				
				11:49:42
S9706	<u>U</u>	USPT	(motion with vector\$1) and	2004-06-
			linear\$ and grid\$1 and (refin\$3	
			with motion vector\$1)	14:40:22
S9705	<u>U</u>	USPT		2004-06-
			with motion vector\$1)	02
				14:39:57
<u>S9704</u>	$\underline{\mathbf{U}}$	USPT	grid\$1 and (refin\$3 with	2004-06-
			motion vector\$1)	02
			( 7 60 11 11 11 11 11 11	14:39:35
<u>S9703</u>	<u>U</u>	USPT	(refin\$3 with motion vector\$1)	2004-06-
1				02 14:39:21
00700	<b>T</b> T	LIODT	(massian miss massages) and	2004-06-
<u>S9702</u>	U	USPT	(motion with vector\$1) and (grid\$1 with (amplified or	02
			amplification or amplify))	14:06:07
S9701	U	USPT	(grid\$1 with (amplified or	2004-06-
39701	<u>U</u>	USF I	amplification or amplify))	02
l			umpinioud on umpiniy))	14:05:33
S9700	U	PGPB,USPT,EPAB,JPAB,DWPI	(hest with mode with motion	2004-06-
32700	<u>U</u>	1010,0011,2110,01110,0	with vector\$1) and (grid\$1	02
			near4 (amplification or	13:57:28
]			amplified or amplifying))	
S9699	U	PGPB,USPT,EPAB,JPAB,DWPI	(grid\$1 near4 (amplification or	2004-06-
			amplified or amplifying))	02
				13:56:54
S9698	<u>U</u>	PGPB,USPT,EPAB,JPAB,DWP		
			amplified or amplifying)) same	
			motion vector\$1	13:56:44
<u>S9697</u>	<u>U</u>	PGPB,USPT,EPAB,JPAB,DWP		
			amplified or amplifying)) same	
			motion vector\$1	13:56:32
<u>S9696</u>	<u>U</u>	PGPB,USPT,EPAB,JPAB,DWP		
			and (amplification or amplified	
00005	T I	DCDD LICHT CDAD IDAD DWD	or amplifying)	13:46:01
<u>S9695</u>	<u>U</u>	PGPB,USPT,EPAB,JPAB,DWP	motion	2004-06 02
				13:44:06
S9694	U	PGPB,USPT,EPAB,JPAB,DWP	[square\$1 and 5745183 nn	2004-06-
39094	<u>U</u>	TOPB, USF 1, EFAB, JI AB, DW1	rsquareor and 3743163.pm.	02
				12:27:53
S9693	U	PGPB,USPT,EPAB,JPAB,DWP	[sum\$1 and 5745183 nn.	2004-06-
	<u> </u>			02
				12:25:46
S9692	U	PGPB,USPT,EPAB,JPAB,DWP	Imotion estimat\$3 and residual	2004-06-
	_		error\$1 and sum with square	02
			with difference\$1	12:13:43
S9691	<u>U</u>	PGPB,USPT,EPAB,JPAB,DWP	I ((best with predict\$3) same	2004-06-



Motion estimat\$3) and residual   02   error\$1 and sum with square   with difference\$1   S9690   U   PGPB,USPT,EPAB,JPAB,DWPI best with predict\$ same motion   2004   estimat\$ and residual error\$1   02   and sum with square with   12:12   difference\$1   S9689   U   PGPB,USPT,EPAB,JPAB,DWPI residual error\$1 and sum with   square with difference\$1   02   12:11   S9688   U   PGPB,USPT,EPAB,JPAB,DWPI sum with square with   2004   difference\$1   02   12:11   S9687   U   USPT   product\$ and 5745183.pn.   2004   01   11:42   S9686   U   USPT   product and 5745183.pn.   2004   01   01   01   01   01   01   01	2:40 06- 1:49 06- 1:22
S9690 U PGPB,USPT,EPAB,JPAB,DWPI best with predict\$ same motion 2004 estimat\$ and residual error\$1 02 and sum with square with difference\$1  S9689 U PGPB,USPT,EPAB,JPAB,DWPI residual error\$1 and sum with 2004 square with difference\$1 02 12:11  S9688 U PGPB,USPT,EPAB,JPAB,DWPI sum with square with difference\$1 02 12:11  S9687 U USPT product\$ and 5745183.pn. 2004.  S9686 U USPT product and 5745183.pn. 2004.	2:40 06- 1:49 06- 1:22
estimat\$ and residual error\$1 02 and sum with square with 12:12 difference\$1  S9689 U PGPB,USPT,EPAB,JPAB,DWPI residual error\$1 and sum with 2004 square with difference\$1 02 12:11  S9688 U PGPB,USPT,EPAB,JPAB,DWPI sum with square with difference\$1 02 12:11  S9687 U USPT product\$ and 5745183.pn. 2004  S9686 U USPT product and 5745183.pn. 2004	2:40 06- 1:49 06- 1:22
and sum with square with difference\$1  S9689 U PGPB,USPT,EPAB,JPAB,DWPI residual error\$1 and sum with square with difference\$1  S9688 U PGPB,USPT,EPAB,JPAB,DWPI sum with square with difference\$1  S9688 U PGPB,USPT,EPAB,JPAB,DWPI sum with square with difference\$1  S9687 U USPT product\$ and 5745183.pn.  S9686 U USPT product and 5745183.pn.  2004-	-06- 1:49 -06- 1:22
S9689 U PGPB,USPT,EPAB,JPAB,DWPI residual error\$1 and sum with 2004 square with difference\$1   02   12:11	-06- 1:49 -06- 1:22
S9689 U PGPB,USPT,EPAB,JPAB,DWPI residual error\$1 and sum with square with difference\$1	1:49 -06- 1:22
S9688 U PGPB,USPT,EPAB,JPAB,DWPI sum with square with   2004   02   12:11   02   02   02   02   02   02   02	1:49 -06- 1:22
S9688 U PGPB,USPT,EPAB,JPAB,DWPI sum with square with difference\$1	-06- 1:22
S9688         U         PGPB,USPT,EPAB,JPAB,DWPI sum with square with difference\$1         2004           S9687         U         USPT         product\$ and 5745183.pn.         2004           S9686         U         USPT         product and 5745183.pn.         2004	-06- 1:22
difference\$1   02   12:11   12:11   12:11   12:11   13:11	1:22
12:11 <u>S9687 U USPT</u> product\$ and 5745183.pn. 2004. 01 11:42 <u>S9686 U USPT</u> product and 5745183.pn. 2004.	
S9687       U       USPT       product\$ and 5745183.pn.       2004-01         01       11:42         S9686       U       USPT       product and 5745183.pn.       2004-01	
01 11:42 <u>S9686 U USPT</u> product and 5745183.pn. 2004.	-00-
11:42 <u>S9686 U USPT</u> product and 5745183.pn. 2004	
<u>S9686</u> <u>U</u> USPT product and 5745183.pn. 2004	2.30
1	
<b>∥</b>	-00-
11:42	).16
S9685 U USPT difference\$1 and 5745183.pn. 2004-	-00-
11:40	1.20
S9684 U USPT absolute and 5745183.pn. 2004-	-06-
01	2.00
11:38	
S9683 U USPT complexit\$ and 6647061.pn. 2004-	-05-
28	
13:55	
S9682 U PGPB,USPT,EPAB,JPAB,DWPI complexit\$ and 6647061.pn. 2004-	-05-
28	
13:55	
S9681 U PGPB,USPT,EPAB,JPAB,DWPI scene and 6647061.pn. 2004-	-05-
28	
13:54	
S9680 U PGPB,USPT,EPAB,JPAB,DWPI scene chang\$3 and 6647061.pn. 2004-	-05-
28	
13:53	
S9679 U PGPB,USPT,EPAB,JPAB,DWPI (4591909  5394249  5543845  2004-	-05-
6438167)![pn] 28	40
13:44	
S9678 U PGPB,USPT,EPAB,JPAB,DWPI (complexit\$ same scene with	<u> </u>
chang\$3) and ((conversion or 28	<b>F</b>
converting or convert\$1) with $\frac{1}{13}$ :40	:54
(image or picture\$1) near3	
information)	0.5
S9677 U PGPB,USPT,EPAB,JPAB,DWPI (difficult\$3 or complexit\$3) 2004-	-05-
and 6587506.pn. 28	
13:33	.20
II.	:38

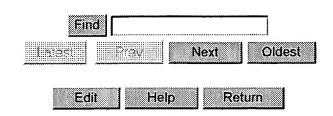








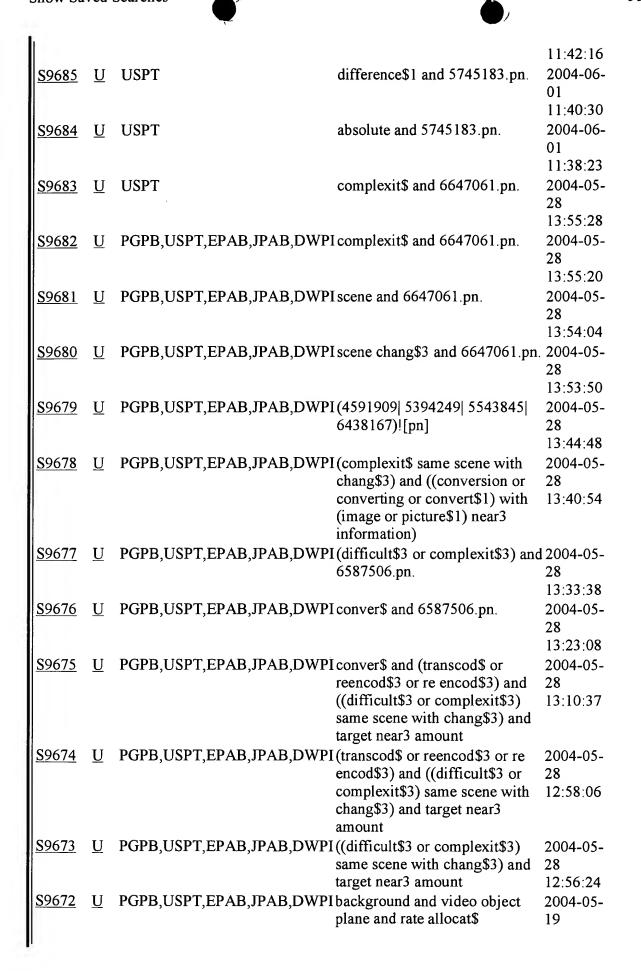
Queries 19323 through 19372.



S#	Updı	t Database	Query	Time	Comment
	_	PGPB,USPT,EPAB,JPAB,DWP	_ •	2004-06-	
		, , , ,	predict\$ and motion estimat\$	03	
			and (grid\$1 with points with	12:08:33	Į.
			vector\$) and motion vector\$1		
S9710	<u>U</u>	PGPB,USPT,EPAB,JPAB,DWPI		2004-06-	
			motion estimat\$ and (grid\$1	03	
			with points with vector\$) and	11:51:04	
			motion vector\$1		
<u>S9709</u>	<u>U</u>	PGPB,USPT,EPAB,JPAB,DWP1		2004-06-	1
			and (grid\$1 with points with	03	
			vector\$) and motion vector\$1	11:50:38	
<u>S9708</u>	<u>U</u>	PGPB,USPT,EPAB,JPAB,DWPI		2004-06-	·
			with points with vector\$) and motion vector\$1	03 11:50:21	
00707		DODD LIGHT ED A D ID A D DYVIN	•		
<u>S9707</u>	<u>U</u>	PGPB,USPT,EPAB,JPAB,DWPI		2004-06- 03	
			vector\$) and motion vector\$1	11:49:42	
S9706	U	USPT	(motion with vector\$1) and	2004-06-	4
39700	<u>U</u>	OSI I	linear\$ and grid\$1 and (refin\$3		1
			with motion vector\$1)	14:40:22	
S9705	U	USPT	linear\$ and grid\$1 and (refin\$3		
37,00	<u>~</u>		with motion vector\$1)	02	
			,	14:39:57	
S9704	U	USPT	grid\$1 and (refin\$3 with motion	2004-06-	
			vector\$1)	02	
				14:39:35	
S9703	<u>U</u>	USPT	(refin\$3 with motion vector\$1)	2004-06-	1,1
				02	
				14:39:21	
<u>S9702</u>	<u>U</u>	USPT	(motion with vector\$1) and	2004-06-	
			(grid\$1 with (amplified or	02	3
00-01		MODE	amplification or amplify))	14:06:07	
<u>S9701</u>	<u>U</u>	USPT	(grid\$1 with (amplified or	2004-06-	
			amplification or amplify))	02	
Į.					



				_	
	<u>S9700</u>	<u>U</u>	PGPB,USPT,EPAB,JPAB,DWP		14:05:33 2004-06-
				with vector\$1) and (grid\$1 near4 (amplification or amplified or amplifying))	02 13:57:28
	<u>\$9699</u>	<u>U</u>	PGPB,USPT,EPAB,JPAB,DWP		2004-06- 02 13:56:54
	<u>S9698</u>	<u>U</u>	PGPB,USPT,EPAB,JPAB,DWP	amplified or amplifying)) same	2004-06- 02
	<u>S9697</u>	<u>U</u>	PGPB,USPT,EPAB,JPAB,DWP	motion vector\$1 (grid\$1 near4 (amplification or amplified or amplifying)) same motion vector\$1	
	<u>S9696</u>	<u>U</u>	PGPB,USPT,EPAB,JPAB,DWP		2004-06-
	<u>S9695</u>	<u>U</u>	PGPB,USPT,EPAB,JPAB,DWP	1 3 0	2004-06- 02 13:44:06
	<u>S9694</u>	<u>U</u>	PGPB,USPT,EPAB,JPAB,DWPI	square\$1 and 5745183.pn.	2004-06- 02 12:27:53
	<u>S9693</u>	<u>U</u>	PGPB,USPT,EPAB,JPAB,DWPI	sum\$1 and 5745183.pn.	2004-06- 02 12:25:46
	<u>S9692</u>	<u>U</u>	PGPB,USPT,EPAB,JPAB,DWPI	motion estimat\$3 and residual error\$1 and sum with square with difference\$1	2004-06- 02 12:13:43
	<u>S9691</u>	<u>U</u>	PGPB,USPT,EPAB,JPAB,DWPI		2004-06- 02 12:13:23
	<u>\$9690</u>	<u>U</u>	PGPB,USPT,EPAB,JPAB,DWPI	with difference\$1 best with predict\$ same motion estimat\$ and residual error\$1 and sum with square with	2004-06- 02 12:12:40
	<u>\$9689</u>	<u>U</u>	PGPB,USPT,EPAB,JPAB,DWPI	difference\$1	2004-06- 02
	<u>\$9688</u>	<u>U</u>	PGPB,USPT,EPAB,JPAB,DWPI	sum with square with difference\$1	12:11:49 2004-06- 02
	<u>\$9687</u>	<u>U</u>	USPT	product\$ and 5745183.pn.	12:11:22 2004-06- 01
	<u>\$9686</u>	<u>U</u>	USPT	product and 5745183.pn.	11:42:30 2004-06- 01
•					



1				11:48:56
<u>S9671</u>	<u>U</u>	PGPB,USPT,EPAB,JPAB,DWP		2004-05-
			plane and rate allocat\$	19
				11:48:48
<u>S9670</u>	<u>U</u>	PGPB,USPT,EPAB,JPAB,DWP	I video object plane and rate allocats	2004-05- 19
			anocats	11:45:49
\$0660	TT	PGPB,USPT,EPAB,JPAB,DWP	Lohiect hased same hit\$1 near3	
32002	<u>U</u>	TOLD, COLL, EL AD, JI AD, DWI	rate with allocat\$)	19
			Tate with uncounty	11:44:54
S9668	U	PGPB,USPT,EPAB,JPAB,DWP	(object based same bit rate	2004-05-
	_	, , , , ,	allocat\$)	19
			,	11:44:20
<u>S9667</u>	<u>U</u>	PGPB,USPT,EPAB,JPAB,DWP	I object based and (bit\$1 near3	2004-05-
			pixel\$1 same (background same	:19
H			foreground))	11:43:14
<u>S9666</u>	<u>U</u>	PGPB,USPT,EPAB,JPAB,DWP	` •	2004-05-
			(background same foreground))	
				11:42:40
<u>S9665</u>	<u>U</u>	PGPB,USPT,EPAB,JPAB,DWP	•	2004-05-
			motion vector\$1)) and refin\$3	19
00664				11:08:40
<u>S9664</u>	<u>U</u>	PGPB,USPT,EPAB,JPAB,DWP		2004-05-
			and motion and wavelet and mallat	18 11:44:54
S9663	U	PGPB,USPT,EPAB,JPAB,DWP		
39003	$\underline{\mathbf{o}}$	FOPD,USP1,EPAD,JPAD,DWP1	ep000543197 or	2004-05- 17
			ep000679032).pn.	09:29:15
S9662	U	USPT	(577678 or 5495292 or	2004-05-
1 57002			ep000543197 or	17
			ep000679032).pn.	09:28:30
<u> </u>				

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